

# Integrating MRI-based geometry, composition and fiber architecture in a finite element model of the human intervertebral disc

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## Abstract

Intervertebral disc degeneration is a common disease that is often related to impaired mechanical function, herniations and chronic back pain. The degenerative process induces alterations of the disc's shape, composition and structure that can be visualized *in vivo* using magnetic resonance imaging (MRI). Numerical tools such as finite element analysis (FEA) have the potential to relate MRI-based information to the altered mechanical behavior of the disc. However, in terms of geometry, composition and fiber architecture, current FE models rely on observations made on healthy discs and might therefore not be well suited to study the degeneration process. To address the issue, we propose a new, more realistic FE methodology based on diffusion tensor imaging (DTI). For this study, a human disc joint was imaged in a high-field MR scanner with proton-density weighted (PD) and DTI sequences. The PD image was segmented and an anatomy-specific mesh was generated. Assuming accordance between local principal diffusion direction and local mean collagen fiber alignment,

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corresponding fiber angles were assigned to each element. Those element-wise fiber directions and PD intensities allowed the homogenized model to smoothly account for composition and fibrous structure of the disc. The disc's *in vitro* mechanical behavior was quantified under tension, compression, flexion, extension, lateral bending and rotation. The six resulting load-displacement curves could be replicated by the FE model, which supports our approach as a first proof of concept towards patient-specific disc modeling.

*Keywords:* Intervertebral disc, diffusion tensor imaging, magnetic resonance imaging, *in vitro* testing, finite element modeling

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**Highlights(3-5 points, max 85 chars each)**

- Distinct collagen fiber lamellae could be visualized using diffusion tensor imaging.
- A fully MRI-based finite element model of a human IVD was generated.
- *In vitro* biomechanical tests in six loading scenarios were conducted.
- The finite element model could reproduce the measured loading curves for the tested range.

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## 1. Introduction

Intervertebral disc (IVD) degeneration is an aberrant cell-mediated response to progressive structural failure which leads to disc herniations and chronic back pain (Adams and Roughley, 2006). In the United States and Switzerland, low back and neck pain are the number one causes of disabilities (IHME, 2016). In the healthy disc, compressive forces are transmitted through the gel-like nucleus pulposus (NP) which is restrained by the annulus fibrosus (AF). With increased degeneration, the IVD hydration level decreases followed by a reduction in disc height. The AF starts to act like a fibrous solid and resists compression directly (Adams and Roughley, 2006). The ensuing structural defects such as radial fissures, ingrowth of innervated fibrous tissue and inflammation (Setton and Chen, 2006) may cause disc herniations or discogenic pain (Brisby, 2006; Yang et al., 2015). From a mechanical point of view, disc degeneration generally increases joint laxity and stiffness (Ellingson et al., 2013). The clinical assessment of IVD pathology (e.g. Pfirrmann scale (Pfirrmann et al., 2001)) is mainly based on MRI and relies on the evidence of gross morphological disruptions (Griffith et al., 2007) and the signal intensity of T2 weighted images (Watanabe et al., 2007).

Finite element (FE) models can help bridging MRI data and disc mechanics (Schmidt et al., 2013). However, current FE models generally employ assumptions about the disc’s composition and the fiber orientation distribution within the AF. These modeling choices result in idealized disc models that are not appropriate when studying disc degeneration. Future FE models will need to integrate the structure and composition of each disc to understand the etiology of disc herniation and back pain. To address the limitations of the current state-of-the-art, we propose a new FE methodology that incorporates a more realistic fibrillar structure and an accurate tissue composition (NP/AF transition). The diffusion of water molecules in a porous media highly depends on its underlying microstruc-

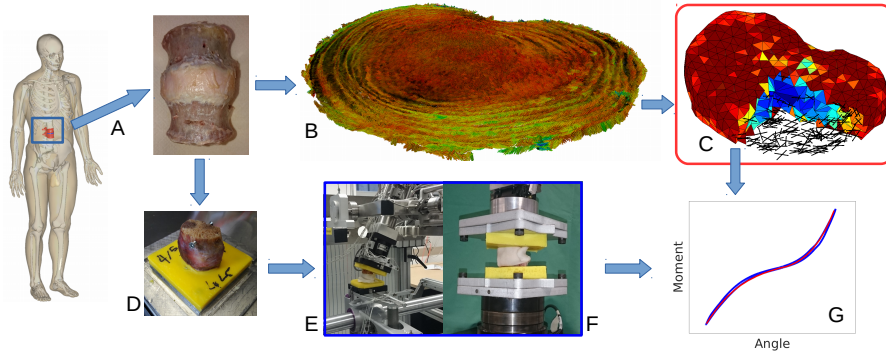


Figure 1: Study overview: A) A human L2-L3 functional spinal unit was prepared and scanned in a 9.4 T MR scanner. Proton-density weighted and B) diffusion tensor images were acquired and processed to generate C) a fully MRI-based finite element model (geometry, composition and anisotropy). D) The sample was embedded and *in vitro* mechanical tests in E) lateral bending, axial rotation, flexion, extension and F) tension and compression were conducted on the sample. G) Using the acquired load-displacement curves, the material parameters were calibrated and the performance of the model was evaluated.

ture (Boss and Stejskal, 1965). Based on this principle, MR diffusion tensor imaging (DTI) allows quantitative measurements of the spatial orientation distribution of anisotropic tissues (Le Bihan et al., 2001; Basser and Jones, 2002). In a previous study, Hsu and colleagues could demonstrate correspondence between principal MR diffusion directions and tissue orientations for AF explants (Hsu and Setton, 1999).

As a very first step, this work aimed to develop and illustrate an MRI-based methodology to create an FE model with specific shape, composition and fiber orientation distribution that can predict the multiaxial compliance of the human IVD (Fig 1). To avoid excessive complexity, only the reversible, time-independent, quasi-static behavior of the IVD was considered.



## 2. Materials and methods

### 2.1. Specimen

A fresh-frozen L2-L3 functional spinal unit was obtained from a 60 years old male donor through an Anatomy Gifts Registry (Hanover, MD). An orthopedic surgeon classified the degeneration grade of the sample as Pfirrmann grade two. With the specimen frozen, the posterior processes, the ligaments and muscular tissues were dissected followed by the transverse sectioning of the cranial and caudal vertebral bodies at mid-body height to isolate the disc joint. The disc joint was wrapped in saline soaked gauze and stored at  $-20^{\circ}\text{C}$  in a double plastic bag.

### 2.2. MR Imaging

The disc was thawed for four hours at room temperature and was placed in a custom-made imaging chamber. To decrease susceptibility effects at the tissue's surface (Benveniste et al., 2000) and prevent dehydration, the chamber was filled with Fomblin Y (Sigma-Aldrich Co., St. Louis, MO), a perfluoropolyether-based lubricant that does not induce any MR-signal and was reported to cause no damage to tissues (Miller et al., 2011). Using a 72 mm birdcage coil (Bruker Biospin MRI GmbH, Ettlingen, Germany), the disc was imaged in a 9.4 T horizontal bore magnet (BioSpec, Bruker Biospin MRI GmbH, Ettlingen, Germany) with the disc's cranial-caudal axis aligned along the axis of the magnet. Axial images (slice thickness: 0.5 mm, in-plane resolution: 0.2 mm, matrix: 270x290, 96 Slices) were acquired using the following protocols (Alkalay et al., 2015):

- Proton-density weighted (PD) FLASH sequence (TE: 5.5 ms, TR: 1755 ms, flip angle:  $60^{\circ}$ ).
- Echo-planar DTI sequence (TE: 29 ms, TR 500 ms, b-value: 700  $\text{s/mm}^2$ , averages: 3). Diffusion gradients were applied at 30 uni-

formly distributed, non-collinear directions, generating 31 diffusion-weighted images (one per direction plus one baseline image). The measurement was performed at room temperature and lasted 10 hours.

### *2.3. Mechanical testing*

With the scans completed, the cranial and caudal vertebral bodies were embedded in polymethylmethacrylate cement (Technovit 3040, Heraeus Kulzer, Hanau, Germany). The sample was kept moist during the embedding process as well as during all following mechanical testing procedures.

**Angular testing:** The embedded disc was secured to a custom six degrees of freedom (DOF), computer-controlled spine testing system (Gédet et al., 2007; Maquer et al., 2014). Under displacement control ( $0.5^\circ/\text{s}$ ), the disc was exposed to pure moments (up to 5 Nm) in flexion, extension, right lateral bending and right axial rotation. Each loading scenario was repeated five times with disc allowed to freely deform about the remaining five DOF thanks to a friction-free air-bearing system. An active optical tracking system (Optotrak Certus, Northern Digital, Canada) was used to record the six DOF motion of the disc. Forces and torques were measured using a six-axis load cell (MC3A, AMTI, U.S.A.).

**Compression/tension testing:** A hydraulic testing system (858 Mini Bionix II, MTS, Eden Prairie, MN) was used for the axial loading scenarios. First, five compressive load cycles up to 350 N at a rate of 10 N/s were performed. The disc was then held at 0 N for 15 minutes (the time equivalent to the loading time) to allow recovery to its original height and an equivalent test was conducted in tension with a maximal load set to 200 N (this force was reduced to prevent the sample from sliding out of the PMMA end-caps). For both tests, the cranial vertebra was allowed to freely translate in the disc's transversal plane with rotational motions constrained. For each test, applied load and resulted displacement were

recorded using the MTS built-in sensors (load cell: model 662.20D-04 and LVDT displacement sensor).

#### *2.4. Image processing*

A pipeline, developed in Matlab (V.15, Mathworks, USA) was used for segmentation, mesh generation and processing the DTI-based fiber data (Fig 2).

**Disc geometry and tissue characterization:** The values of the PD MR images were highest at the highly hydrated inner NP. Using the assumption that for a given sub-region, the amount of collagen fibers is inversely proportional to the amount of water, the PD images were inverted and normalized, leading to a new voxel value ( $\lambda$ ). These new voxel values were later used to scale the contribution of the collagen fibers for each finite element. The geometry of the disc was segmented using an Otsu threshold-based algorithm (Otsu, 1979).

**DTI-based fiber orientations:** The DTI data set (31 diffusion-weighted images) was processed to yield a single diffusion tensor per voxel. To prevent negative eigenvalues, DTI tensors were computed using an iterative method proposed by Niethammer and colleagues (Niethammer et al., 2006). The fundamental assumption of this work is that this principal eigenvector directly corresponds to the local mean fiber orientation (Hsu and Setton, 1999). Hence, a spectral decomposition was conducted on each tensor with only the eigenvector corresponding to the largest eigenvalue (direction of highest diffusion) retained for further processing. Fraction anisotropy (FA), a scalar measure describing the degree of anisotropy of a diffusion process ( $FA = 0$  = isotropic diffusion,  $FA = 1$  = highly oriented diffusion) (Le Bihan et al., 2001), was computed from the resulting eigenvalues.

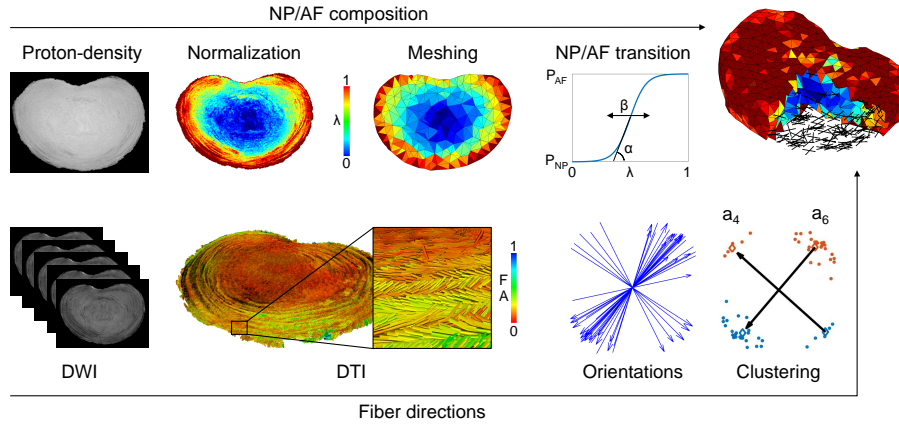


Figure 2: Proton-density weighted images were acquired, normalized to the highest signal intensity found within the annulus fibrosus (AF), segmented and the disc volume converted into a tetrahedral mesh. The normalized voxel values,  $\lambda$ , were assigned to each of the tetrahedrons and used to smoothly distinguish the material properties of the inner nucleus pulposus (NP) and the surrounding AF using a sigmoid function characterized by  $\alpha$  and  $\beta$ . Diffusion tensors (DTI) were estimated from the DWI images, with only the eigenvectors corresponding to the largest eigenvalues retained and colored by fraction anisotropy (FA). From the computed DTI eigenvector data, and for each tetrahedron, a k-mean clustering algorithm was used to compute and assign the main fiber directions ( $a_4$  and  $a_6$ ).

### 2.5. Finite element modeling

Using the ISO2MESH toolbox (Fang and Boas, 2009), a tetrahedral mesh (quadratic C3D10 tetrahedrons, mean edge length = 2.5 mm) was generated from the segmented disc geometry. Instead of simulating individual collagen fiber bundles, a homogenization approach (Hill, 1963) was used. Each homogenized element represents the average mechanical behavior of the underlying structure. The contribution of the individual annular fibers is implicitly accounted for by the model's constitutive law. Considering a small sub-volume of the AF, independent of the number of collagen fiber layers included, reveals that two main directions of collagen fibers have to be defined for each finite element. For this purpose, a spherical sub-volume was defined at the center of gravity of each tetrahedron. For each sphere, all DTI eigenvectors located within were selected and a k-mean clustering algorithm applied. This clustering algorithm regrouped all start- and end-points of the eigenvectors into four point-clouds. Finally, the centers of gravity of opposite clouds were connected with two vectors. These vectors (a4 and a6) represent the mean fiber orientations for the given sub-volume (fig. 2).

To catch both principal directions, this sub-volume has to include at least two adjacent collagen fiber layers. The diameters for these layers were reported to vary between 0.1 mm to 0.5 mm, depending on age and position within the disc (Marchand and Ahmed, 1990). A sensitivity study was performed to define the size of this sub-volume. While too small volumes are prone to outliers, too large volumes reduce the local sensitivity of the method. Values between 0.6 mm and 1 mm were found to yield stable, yet qualitatively and quantitatively correct results (the resulting vectors followed the circumferential shape of the AF, and the angles with respect to the transversal were within the previously reported range). Taking the mean value of this stable range, the final radius was set to 0.8 mm.

To scale the local amount of collagen fibers and the compressibility of each

finite element, the average value of the normalized PD image,  $\lambda$ , within the same spherical sub-volume was computed. Finally, the specific values of  $\lambda$ ,  $\mathbf{a}_4$  and  $\mathbf{a}_6$  were assigned to the corresponding tetrahedral element.

The low sensitivity of the FE model to the mesh size was verified by varying the size of the tetrahedrons (2 to 3 mm mean edge length).

Based on the Holzapfel-Gasser-Odgen model for simulating anisotropic hyperelastic fiber-reinforced materials (Holzapfel et al., 2000; Eberlein et al., 2001), we implemented a time-independent constitutive law with a free energy function (Eq. 1). The law incorporates a separate isotropic term, corresponding to the ground substance (Eq. 2), and an anisotropic term with two normalized vectors ( $\mathbf{a}_4$  and  $\mathbf{a}_6$ ), corresponding to the two main fiber directions (Eq. 3). The main difference to previous models lies in the fact, that  $\mathbf{a}_4$  and  $\mathbf{a}_6$  are not defined based on assumptions, but originate directly from MR images. Furthermore, the full anisotropic invariants (Eq. 7) were used as highlighted by Nolan and colleagues (Nolan et al., 2014).

$$\psi = \psi_{fibers} + \psi_{GroundSubstance} \quad (1)$$

$$\psi_{GroundSubstance}(\mathbf{C}) = \frac{\kappa}{2}(J-1)^2 + \frac{\mu}{2}(J^{-\frac{2}{3}}I_1 - 3) \quad (2)$$

$$\psi_{fibers}(\mathbf{C}, \mathbf{a}_4, \mathbf{a}_6) = \frac{k_1}{2} \sum_{4,6} (I_i - 1)^{2k_2} \quad (3)$$

$$\mathbf{C} = \mathbf{F}^T \mathbf{F} \quad (4)$$

$$J = Det(\mathbf{C})^{\frac{1}{2}} \quad (5)$$

$$I_1 = tr(\mathbf{C}) \quad (6)$$

$$I_{4,6}(\mathbf{C}, \mathbf{a}_{4,6}) = \mathbf{a}_{4,6} \cdot \mathbf{C} \mathbf{a}_{4,6} \quad (7)$$

$$\kappa = \frac{1}{1 + \exp(-\alpha(\lambda - \beta))} (\kappa_{AF} - \kappa_{NP}) + \kappa_{NP} \quad (8)$$

$$k_1 = \frac{1}{1 + \exp(-\alpha(\lambda - \beta))} (k_{1AF} - k_{1NP}) + k_{1NP} \quad (9)$$

$k_1$  corresponds to the stiffness of the fibers and  $k_2$  to their non-linearity. The deformations and reorientations of the fibers are given by the invariants  $I_4$  and  $I_6$  which are derived from the deformation gradient  $\mathbf{F}$ . At the material level, the fibers are only active under tension ( $\psi_{fibers_{4,6}} = 0$  if  $I_{4,6} < 1$ ).  $\kappa$  is the resistance against volumetric deformations (bulk modulus),  $\mu$  the resistance against isochoric deformations (shear modulus). As in-plane shear deformations are prevented by the fibers, the shear term in the isotropic energy equation could be simplified, reducing the number of material parameters. However, this caused numerical instability at the beginning of the loading cycle, especially in compression, as the fibers become only active when stretched. To avoid this,  $\mu$  was manually set to a low value (0.05 MPa) for all elements.  $\kappa$  and  $k_1$  are not material parameters per se, but are scaled using the MRI-based  $\lambda$  value of each element and a smooth sigmoid function characterized by  $\alpha$  and  $\beta$  (Eq. 8 and Eq. 9).  $\alpha$  determines how quickly  $\kappa$  and  $k_1$  change from minimal to maximal values (NP values to AF values or vice versa), corresponding to the size of the transition zone between NP and AF.  $\beta$  defines the ratio between NP and AF.

The time-independent constitutive law was implemented as an Abaqus (6.13 Dassault Systemes, France) user material (UMAT), with the simulation's boundary conditions defined precisely as the experimental test conditions.

## 2.6. Calibration

All simulations were performed in Abaqus (6.13 Dassault Systemes, France). As the disc's time-depended response was not simulated, the measured load-displacement curves were further processed prior to their use for the calibration process. For flexion, extension, lateral bending and axial rotation loading scenarios, the mean curves of the measured hysteresis were used. For axial compression and tension, the drift caused by the disc's

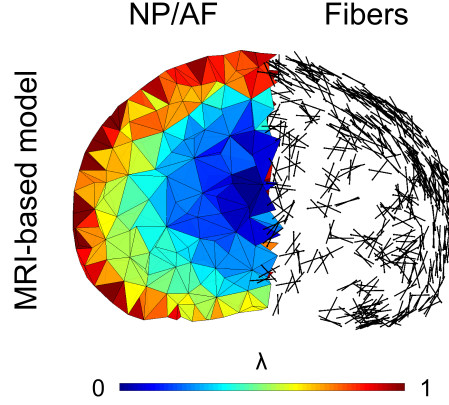


Figure 3: The fully MRI-based model accounts for the smooth transition between nucleus pulposus (NP) and annulus fibrosus (AF). The presentation of the fibers demonstrates the clear distinction between the outer AF, showing spatially organized fibers, becoming increasingly disorganized towards the inner NP.

time-dependent deformation was subtracted from each cycle, with each cycle shifted to the origin. A mean curve was then computed from the combined hysteresis loops. The limit values of  $\kappa$  ( $\kappa_{AF}$ ,  $\kappa_{NP}$ ),  $k_1$  ( $k_{1AF}$ ,  $k_{1NP}$ ) as well as  $k_2$  (for which the same value was assigned to all elements),  $\alpha$  and  $\beta$  were determined upon calibration of the FE model vs. the experimental data. For this purpose, a Particle Swarm Optimization (PSO) (Clerc and Kennedy, 2002) was used to minimize the difference between the experimental and simulated data curves to allow calibration of the tissues material parameters (Maquer et al., 2015). The optimization lasted 12 hours using four CPUs. Once completed, the obtained load-displacement curves were compared to the experimental load-displacement data.

### 3. Results

#### 3.1. MRI-derived disc structure

Computation of the diffusion tensors revealed a disorganized distribution of fibers with almost isotropic diffusivity at the center of the NP ( $FA <$



$\mu$ [MPa]	$\kappa_{NP}$ [MPa]	$\kappa_{AF}$ [MPa]	$k_{1NP}$ [MPa]	$k_{1AF}$ [MPa]	$k_2$ [-]	$\alpha$ [-]	$\beta$ [-]
0.05	24.3	3.1	580	2219	1.2	68	0.28

Table 1: Material parameters resulting from the calibration of the models with the *in vitro* load-displacement data.

0.2). Extending outwards towards the outer portion of the AF showed a clear increase in organization, revealing a layer-based arrangement with the diffusion tensors becoming increasingly anisotropic (FA reaching up to 0.5)(Fig 2). The final fiber angles assigned to the elements ranged from  $25^\circ$  to  $50^\circ$  with respect to the transverse plane. Although having no physical units,  $\lambda$  values computed from the normalization of the PD images accounted for the varying composition of the sample (Fig. 3).

### 3.2. Finite element predictions

Figure 4 presents the experimental and FE predicted moment-angle and force-displacement response of the disc joint. Generally, the FE model agrees with the *in vitro* load-displacement curves of all loading cases. A high fiber stiffness ( $k_1$ ) and a relatively soft ground substance ( $\kappa$ ) were found to provide the best agreement with all the *in vitro* load cases. To verify that the fibers were the main contributor to the disc’s compliance, the fiber term was switched off, leaving the model solely relying on its ground substance (Fig 4: MRI-based model w/o fibers). In this case, the model lost most of its stiffness in all directions.

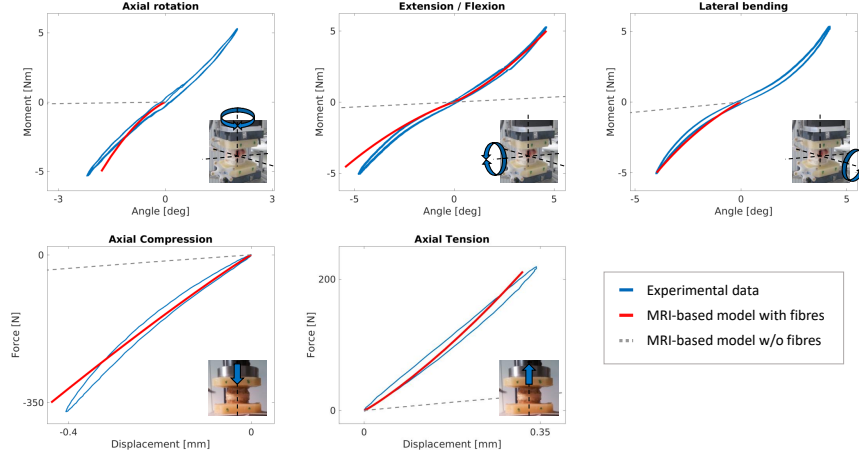


Figure 4: The DTI MR-based model replicates the *in vitro* load-displacement curves. The gray curves show the compliance of the model if the contribution of the fibers is switched off.

#### 4. Discussion

This work aimed to demonstrate the potential of diffusion tensor MRI in FE modeling of the human IVD. A PD sequence was used to generate a mesh based on the disc's geometry and to map its composition to the model, while the change in local fiber orientation within each element was directly computed from DTI measurements. With disc's composition and fiber architecture treated as a continuum, the outcome of such a model may depend on the homogenization procedure (Hill, 1963). Accordingly, the model's low sensitivity to mesh size and material mapping sub-volume was verified. Independent of the underlying tissue structure, the generation of such homogenized FE models can be fully automatized, which constitutes a distinct advantage for high-throughput *in vitro* studies or potential clinical applications.

The MRI-based model successfully reproduced the six different loading scenarios despite the simple constitutive law. The presented methodology was applied to one single sample, which constitutes its biggest limitation.

A direct comparison to idealized FE models was not undertaken as this would require a more substantial number of samples. The proposed model is based on high-field MRI images. To be considered for potential clinical applications, the methodology will have to be adapted to clinical MRI scanners. The lower field strength of clinical MR scanners will lead to a reduced image resolution. Considering the alignment of the collagen fiber bundles, this will not induce major changes for the circumferential angle of the fibers, as this angle remains relatively constant in a given sub-region. However, because of the angle alterations between adjacent collagen layers, the angle of the fibers with respect to the transversal plane will suffer from a decreased image resolution, and eventually reach a point where adjacent layers cannot be distinguished. In this case, the angles from each layer will cancel each other and a mean direction of approximately  $0^\circ$  will be measured. We confirmed on the 9.4 T scanner that the fibers families can be distinguished on images at a resolution of 0.5 mm, corresponding to the resolution of a clinical 3 T scanner. Nevertheless, further work is necessary to implement the methodology on a 3 T scanner. If unsuccessful, the methodology could be implemented on a 7 T scanner.

Although a previous study suggested that main diffusion directions correspond to the collagen fiber orientations (Hsu and Setton, 1999), hard evidence proving this is currently lacking. However, the lamellar criss-cross organization (Fig. 2) and angular range ( $25\text{-}50^\circ$ ) of the main diffusion directions compare favorably with histological observations (Marchand and Ahmed, 1990). Nevertheless, future work should compare DTI directions to *in vitro* 3D histology (Adam et al., 2015).

In its current state, the model neglected all time-dependent effects and a reversible, quasi-static behavior was assumed. The sample was prevented from drying out by keeping it moist during mechanical testing. No visible loss of water content or disc height could be observed, however, these variables were not measured. *Ex vivo* mechanical tests were performed

with similarly low rates in all loading modes to minimize time-dependent effects. The loading curves in tension and compression (loading modes with the highest volumetric strains) were high-pass filtered to subtract drifts caused by poroelasticity before using them as input for the material parameter calibration. We acknowledge that this did not completely remove all time-dependent effects in our measurements. However, adding anisotropic and heterogeneous poro-viscoelasticity to our newly developed MRI-based model was clearly beyond the scope of this study.

Patient-specific FE models of the degenerating IVD could be useful to better understand the degeneration process and estimate the risk of herniation or instability-related back-pain, but this perspective will require a more systematic validation of the methodology with clinical MRI images.

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### **Conflict of interest**

The authors have no conflict of interest to declare.

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